

## AN IMPROVED ESTIMATOR FOR POPULATION MEAN USING AUXILIARY INFORMATION IN STRATIFIED RANDOM SAMPLING

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### ABSTRACT

In the present study we propose a new estimator for population mean  $\bar{Y}$  of the study variable  $y$  in the case of stratified random sampling using the information based on auxiliary variable  $x$ . An expression for the mean squared error (MSE) of the proposed estimator is derived up to the first order of approximation. The theoretical conditions have also been verified by a numerical example. An empirical study demonstrates the efficiency of the suggested estimator over sample mean estimator, usual separate ratio, separate product estimator and other proposed estimators.

**Key words:** study variable, auxiliary variable, stratified random sampling, separate ratio estimator, bias and mean squared error.

### 1. Introduction

The problem of estimating the population mean in the presence of an auxiliary variable has been widely discussed in the finite population sampling literature. Many ratio, product and regression methods of estimation are good examples in this context. Diana (1993) suggested a class of estimators of the population mean using one auxiliary variable in the stratified random sampling and examined the MSE of the estimators up to the  $k^{\text{th}}$  order of approximation. Kadilar and Cingi (2003), Singh et al. (2007), Singh and Vishwakarma (2008) as well as Koyuncu and Kadilar (2009) proposed estimators in stratified random sampling. Bahl and Tuteja (1991) and Singh et al. (2007) suggested some exponential ratio type estimators.

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Consider a finite population of size  $N$  is divided into  $L$  strata such that  $\sum_{h=1}^L N_h = N$ , where  $N_h$  is the size of  $h^{\text{th}}$  stratum ( $h=1,2,\dots,L$ ). We select a sample of size  $n_h$  from each stratum by simple random sampling without replacement (SRSWOR), such that  $\sum_{h=1}^L n_h = n$ , where  $n_h$  is the stratum sample size. Let  $(y_{hi}, x_{hi}, z_{hi})$  denote the observed values of  $y$ ,  $x$ , and  $z$  on the  $i^{\text{th}}$  unit of the  $h^{\text{th}}$  stratum, where  $i=1, 2, 3, \dots, N_h$ .

We use the following notations:

$$\bar{y}_{st} = \sum_{h=1}^L W_h \bar{y}_h, \quad \bar{y}_h = \frac{1}{n_h} \sum_{i=1}^{n_h} y_{hi}, \quad \bar{Y}_h = \frac{1}{N_h} \sum_{i=1}^{n_h} \bar{Y}_{hi},$$

$$Y = \bar{Y}_{st} = \sum_{h=1}^L W_h \bar{Y}_h, \quad w_h = \frac{N_h}{N}.$$

Let

$$S_{yh}^2 = \sum_{i=1}^{N_h} \frac{(\bar{y}_h - \bar{Y}_h)^2}{N_h - 1}, \quad S_{xh}^2 = \sum_{i=1}^{N_h} \frac{(\bar{x}_h - \bar{X}_h)^2}{N_h - 1}$$

$$S_{yxh} = \sum_{i=1}^{N_h} \frac{(\bar{x}_h - \bar{X}_h)(\bar{y}_h - \bar{Y}_h)}{N_h - 1} \quad \text{and} \quad f_h = \frac{1}{n_h} - \frac{1}{N_h}$$

## 2. Established estimators

When the population mean  $\bar{X}_h$  of the stratum  $h$  of the auxiliary variable  $x$  is known then the usual separate ratio and product estimators for the population mean  $\bar{Y}$  are respectively given as

$$t_1 = \sum_{h=1}^L W_h \bar{y}_h \frac{\bar{X}_h}{X_h} \tag{2.1}$$

$$t_2 = \sum_{h=1}^L W_h \bar{y}_h \frac{\bar{X}_h}{\bar{X}_h} \tag{2.2}$$

Following Bahl and Tuteja (1991), we propose the following ratio and product exponential estimators

$$t_3 = \sum_{h=1}^L W_h \bar{y}_h \exp\left(\frac{\bar{X}_h - \bar{X}_h}{\bar{X}_h + \bar{X}_h}\right) \tag{2.3}$$

$$t_4 = \sum_{h=1}^L W_h \bar{y}_h \exp\left(\frac{\bar{X}_h - \bar{X}_h}{\bar{X}_h + \bar{X}_h}\right) \tag{2.4}$$

The MSEs of these estimators are respectively given by

$$MSE(t_1) = \sum_{h=1}^L W_h^2 f_h \left[ S_{yh}^2 + R_h^2 S_{xh}^2 - 2R_h S_{yxh} \right] \tag{2.5}$$

$$MSE(t_2) = \sum_{h=1}^L W_h^2 f_h \left[ S_{yh}^2 + R_h^2 S_{xh}^2 + 2R_h S_{yxh} \right] \tag{2.6}$$

$$MSE(t_3) = \sum_{h=1}^L W_h^2 f_h \left[ S_{yh}^2 + \frac{R_h^2}{4} S_{xh}^2 - R_h S_{yxh} \right] \tag{2.7}$$

$$MSE(t_4) = \sum_{h=1}^L W_h^2 f_h \left[ S_{yh}^2 + \frac{R_h^2}{4} S_{xh}^2 + R_h S_{yxh} \right] \tag{2.8}$$

The usual regression estimator of the population mean  $\bar{Y}$  is

$$t_{lr} = \sum_{h=1}^L w_h \left[ \bar{y}_h + b_h (\bar{X}_h - \bar{x}_h) \right] \tag{2.9}$$

The MSE of the regression estimator is given by

$$\text{var}(t_{lr}) = \sum_{h=1}^L W_h^2 f_h S_{yh}^2 (1 - \rho_h^2) \tag{2.10}$$

The variance of the usual sample mean estimator  $\bar{y}_h$  is given as

$$\text{var}(\bar{y}_{st}) = \sum_{h=1}^L W_h^2 f_h S_{yh}^2 \tag{2.11}$$

Yadav et al. (2011) proposed an exponential ratio-type estimator for estimating  $\bar{Y}$  as

$$t_R = \sum_{h=1}^L w_h \bar{y}_h \exp\left(\frac{\bar{X}_h - \bar{x}_h}{\bar{X}_h + (a_h - 1)\bar{x}_h}\right) \tag{2.12}$$

The MSE of the estimator  $t_R$  is given by

$$MSE(t_R) = \sum_{h=1}^L W_h^2 f_h \left[ S_{yh}^2 + \frac{R_h^2}{a_h^2} S_{xh}^2 - 2 \frac{R_h}{a_h} S_{yxh} \right] \tag{2.13}$$

At the optimum value of  $a_h$  the MSE of the estimator  $t_R$  is equal to the MSE of the regression estimator  $t_{lr}$  given in equation (2.9).

### 3. The proposed estimator

Motivated by Singh and Solanki (2012), we propose an estimator of population mean  $\bar{Y}$  of the study variable  $y$  as

$$t_p = \sum_{h=1}^L w_h \left[ \lambda_1 \bar{y}_h + \lambda_2 (\bar{X}_h - \bar{x}_h) \right] \left\{ 2 - \left( \frac{\bar{X}_h}{\bar{x}_h} \right) \exp \left( \frac{\bar{X}_h - \bar{x}_h}{\bar{X}_h + \bar{x}_h} \right) \right\} \quad (3.1)$$

To obtain the bias and MSE of  $t_p$ , we write

$$\bar{y}_{st} = \sum_{h=1}^L w_h \bar{y}_h = \bar{Y}(1 + e_0), \quad \bar{x}_{st} = \sum_{h=1}^L w_h \bar{x}_h = \bar{X}(1 + e_1)$$

such that

$$E(e_{0h}) = E(e_{1h}) = 0,$$

and 
$$E(e_0^2) = \frac{\sum_{h=1}^L W_h^2 f_h S_{y_h}^2}{\bar{Y}^2}, \quad E(e_1^2) = \frac{\sum_{h=1}^L W_h^2 f_h S_{x_h}^2}{\bar{X}^2}, \quad E(e_0 e_1) = \frac{\sum_{h=1}^L W_h^2 f_h S_{y x_h}^2}{\bar{Y} \bar{X}}.$$

Expressing equation (3.1) in terms of es, we have

$$\begin{aligned} t_p &= \sum_{h=1}^L w_h \left\{ \left[ \lambda_1 \bar{Y}_h (1 + e_0) - \lambda_2 \bar{X}_h \left[ 2 - (1 + e_1)^{-1} \exp \left( -\frac{e_1}{2} + \frac{e_1^2}{4} \right) \right] \right] \right\} \\ &= \sum_{h=1}^L w_h \left\{ \left[ \lambda_1 \bar{Y}_h (1 + e_0) - \lambda_2 \bar{X}_h \left[ 1 + \frac{3e_1}{2} - \frac{15}{8} e_1^2 \right] \right] \right\} \end{aligned} \quad (3.2)$$

By neglecting the terms of  $e$ 's power greater than two in expression (3.2), we obtain

$$\begin{aligned} t_p - \bar{Y} &= \sum_{h=1}^L w_h \left[ \lambda_1 \bar{Y}_h (1 + e_0) - \lambda_2 \bar{X}_h e_1 + \frac{3}{2} \lambda_1 \bar{Y}_h e_1 + \frac{3}{2} \lambda_1 \bar{Y}_h e_0 e_1 \right. \\ &\quad \left. - \frac{3}{2} \lambda_2 \bar{X}_h e_1^2 - \frac{15}{8} \lambda_1 \bar{Y}_h e_1^2 - \bar{Y}_h \right] \end{aligned} \quad (3.3)$$

Taking expectations on both sides of (3.3), we have the bias of the estimator  $t_p$  up to the first order of approximation as

$$B(t_p) = \sum_{h=1}^L w_h \left\{ \bar{Y}_h (\lambda_1 - 1) + \frac{3}{2} \lambda_1 f_h \frac{S_{y x_h}}{\bar{X}_h} - \frac{3}{2} \lambda_2 f_h \frac{S_{x_h}^2}{\bar{X}_h} - \frac{15}{8} \lambda_1 \bar{R}_h \frac{S_{x_h}^2}{\bar{X}_h} \right\} \quad (3.4)$$

Squaring both sides of (3.3) and neglecting the terms with power greater than two, we have

$$\begin{aligned}
 (t_p - \bar{Y})^2 &= \sum_{h=1}^L w_h^2 \left[ \lambda_1 \bar{Y}_h (1 + e_0) - \lambda_2 \bar{X}_h e_1 + \frac{3}{2} \lambda_1 \bar{Y}_h e_1 - \bar{Y}_h \right]^2 \\
 (t_p - \bar{Y})^2 &= \sum_{h=1}^L w_h^2 \left[ \lambda_1^2 \left( \bar{Y}_h^2 e_0 + \bar{Y}_h^2 + \frac{9}{4} \bar{Y}_h^2 e_1^2 + 3 \bar{Y}_h^2 e_0 e_1 \right) + \lambda_2^2 \bar{X}_h^2 \right. \\
 &\quad \left. + \bar{Y}_h^2 - 2 \lambda_1 \bar{Y}_h^2 - 2 \lambda_1 \lambda_2 \bar{Y}_h \bar{X}_h e_0 e_1 - 3 \lambda_1 \lambda_2 \bar{Y}_h \bar{X}_h e_1^2 \right]
 \end{aligned}
 \tag{3.5}$$

Taking expectations of both sides of (3.5), we have the mean squared error of the estimator  $t_p$  up to the first order of approximation as

$$\text{MSE}(t_p) = \lambda_1^2 P_1 + \lambda_2^2 P_2 - 2 \lambda_1 \lambda_2 P_3 - 3 \lambda_1 \lambda_2 P_4 - 2 \lambda_1 \sum_{h=1}^L w_h^2 \bar{Y}_h^2 + \sum_{h=1}^L w_h^2 \bar{Y}_h^2
 \tag{3.6}$$

where,

$$\left. \begin{aligned}
 P_1 &= \sum_{h=1}^L W_h^2 f_h S_{yh}^2 + \frac{9}{4} \sum_{h=1}^L W_h^2 f_h R_h^2 S_{xh}^2 + \sum_{h=1}^L W_h^2 \bar{Y}_h^2 + 3 \sum_{h=1}^L W_h^2 f_h R_h S_{yhx} \\
 P_2 &= \sum_{h=1}^L W_h^2 f_h S_{xh}^2 \\
 P_3 &= \sum_{h=1}^L W_h^2 f_h S_{yhx} \\
 P_4 &= \sum_{h=1}^L W_h^2 f_h R_h S_{xh}^2
 \end{aligned} \right\}
 \tag{3.7}$$

Partially differentiating expression (3.6) with respect to  $\lambda_1$  and  $\lambda_2$ , we get the optimum values of  $\lambda_1$  and  $\lambda_2$  as

$$\lambda_1(\text{opt}) = \frac{4P_2 \sum_{h=1}^L w_h^2 \bar{Y}_h^2}{4P_1 P_2 - [2P_3 + 3P_4]^2} \quad \text{and} \quad \lambda_2(\text{opt}) = \frac{2[2P_3 + 3P_4] \sum_{h=1}^L w_h^2 \bar{Y}_h^2}{4P_1 P_2 - [2P_3 + 3P_4]^2}$$

Substituting these values of  $\lambda_1$  and  $\lambda_2$  in expression (3.7), we get the minimum value of the  $\text{MSE}(t_p)$ .

#### 4. Numerical study

For numerical study we use the data set used earlier by Kadilar and Cingi (2003). In this data set, Y is the apple production amount and X is the number of apple trees in 854 villages of Turkey in 1999. The population information about this data set is given in Table 4.1. The indices 1,2,...,6 indicate the strata.

**Table 4.1.** Population data

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N=854	n=140				
N <sub>1</sub> =106	N <sub>2</sub> =106	N <sub>3</sub> =94	N <sub>4</sub> =171	N <sub>5</sub> =204	N <sub>6</sub> =173
n <sub>1</sub> =9	n <sub>2</sub> =17	n <sub>3</sub> =38	n <sub>4</sub> =67	n <sub>5</sub> =7	n <sub>6</sub> =2
$\bar{X}_1 = 24375$	$\bar{X}_2 = 27421$	$\bar{X}_3 = 72409$	$\bar{X}_4 = 74365$	$\bar{X}_5 = 26441$	$\bar{X}_6 = 9844$
$\bar{Y}_1 = 1536$	$\bar{Y}_2 = 2212$	$\bar{Y}_3 = 9384$	$\bar{Y}_4 = 5588$	$\bar{Y}_5 = 967$	$\bar{Y}_6 = 404$
$\beta_{x_1} = 25.71$	$\beta_{x_2} = 34.57$	$\beta_{x_3} = 26.14$	$\beta_{x_4} = 97.60$	$\beta_{x_5} = 27.47$	$\beta_{x_6} = 28.10$
C <sub>x1</sub> =2.02	C <sub>x2</sub> =2.10	C <sub>x3</sub> =2.22	C <sub>x4</sub> =3.84	C <sub>x5</sub> =1.72	C <sub>x6</sub> =1.91
C <sub>y1</sub> =4.18	C <sub>y2</sub> =5.22	C <sub>y3</sub> =3.19	C <sub>y4</sub> =5.13	C <sub>y5</sub> =2.47	C <sub>y6</sub> =2.34
S <sub>x1</sub> =49189	S <sub>x2</sub> =57461	S <sub>x3</sub> =160757	S <sub>x4</sub> =285603	S <sub>x5</sub> =45403	S <sub>x6</sub> =18794
S <sub>y1</sub> =6425	S <sub>y2</sub> =11552	S <sub>y3</sub> =29907	S <sub>y4</sub> =28643	S <sub>y5</sub> =2390	S <sub>y6</sub> =946
$\rho_1 = 0.82$	$\rho_2 = 0.86$	$\rho_3 = 0.90$	$\rho_4 = 0.99$	$\rho_5 = 0.71$	$\rho_6 = 0.89$
f <sub>1</sub> = 0.102	f <sub>2</sub> = 0.049	f <sub>3</sub> = 0.016	f <sub>4</sub> = 0.009	f <sub>5</sub> = 0.138	f <sub>6</sub> = 0.006
w <sub>1</sub> <sup>2</sup> = 0.015	w <sub>2</sub> <sup>2</sup> = 0.015	w <sub>3</sub> <sup>2</sup> = 0.012	w <sub>4</sub> <sup>2</sup> = 0.04	w <sub>5</sub> <sup>2</sup> = 0.057	w <sub>6</sub> <sup>2</sup> = 0.041

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To compare the efficiency of the proposed estimator we have computed the percent relative efficiencies (PREs) of the estimators with respect to the usual unbiased estimator  $\bar{y}_{st}$  using the formula:

$$PRE\left(t, \bar{y}_{st}\right) = \frac{MSE\left(\bar{y}_{st}\right)}{MSE(t)} * 100, \text{ where } t = (t_1, t_2, t_3, t_{lr}, t_p)$$

The findings are given in the Table 4.2.

**Table 4.2.** Percent relative efficiencies (PREs) of estimators

S. No.	ESTIMATORS	PREs
1	$\bar{y}_{st}$	100
2	$t_1$	423.20
3	$t_2$	37.60
2	$t_3$	199.14
3	$t_4$	12.83
4	$t_{lr}$	629.03
5	$t_R$	629.03
6	$t_p$	789.87

### 5. Conclusion

In this paper we have proposed a new estimator of the population mean of the study variable using auxiliary variables. Expressions for bias and MSE of the estimator are derived up to first order of approximation. The proposed estimator is compared with the usual mean estimator and other considered estimators. A numerical study is carried out to support the theoretical results. From Table 4.2. it is clear that the proposed estimator  $t_p$  is more efficient than the unbiased sample mean estimator  $\bar{y}_{st}$ , the usual ratio and product estimators  $t_1$  and  $t_2$ , the usual exponential ratio and product type estimators  $t_3$  and  $t_4$ , and Yadav et al. (2011) estimator  $t_R$ .

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